Galerkin Finite Element Model for Heat Transfer

Introductory Course on Multiphysics Modelling

TOMASZ G. ZIELIŃSKI

bluebox.ippt.pan.pl/~tzielins/

Institute of Fundamental Technological Research of the Polish Academy of Sciences

Warsaw • Poland



1 Notation remarks

- **Notation remarks**
- **Local differential formulation**
 - Partial Differential Equation
 - Initial and boundary conditions
 - Initial-Boundary-Value Problem

- 1 Notation remarks
- 2 Local differential formulation
 - Partial Differential Equation
 - Initial and boundary conditions
 - Initial-Boundary-Value Problem
- 3 Global integral formulations
 - Test functions
 - Weighted formulation and weak variational form

- 1 Notation remarks
- 2 Local differential formulation
 - Partial Differential Equation
 - Initial and boundary conditions
 - Initial-Boundary-Value Problem
- 3 Global integral formulations
 - Test functions
 - Weighted formulation and weak variational form
- 4 Matrix formulations
 - Approximation
 - Transient heat transfer (ordinary differential equations)
 - Stationary heat transfer (algebraic equations)

- **Notation remarks**
- - Partial Differential Equation
 - Initial and boundary conditions
 - Initial-Boundary-Value Problem
- - Test functions
 - Weighted formulation and weak variational form
- - Approximation
 - Transient heat transfer (ordinary differential equations)
 - Stationary heat transfer (algebraic equations)

Notation remarks

Notation remarks

- The **index notation** is used with summation over the index i.
- Consequently, the **summation rule** is also applied for the approximation expressions, that is, over the indices $r, s = 1, \dots N$ (where N is the number of degrees of freedom).
- The symbol (...)_i means a (generalized) invariant partial **differentiation** over the *i*-th coordinate:

$$(\ldots)_{|i|} = \frac{\partial(\ldots)}{\partial x_i}$$
.

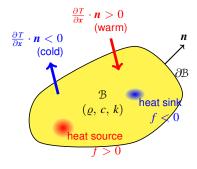
The invariance involves the so-called Christoffel symbols (in the case of curvilinear systems of reference).

Symbols dV and dS are completely omitted in all the integrals presented below since it is obvious that one integrates over the specified domain or boundary. Therefore, one should understand that:

$$\int_{\mathcal{B}} (\ldots) = \int_{\mathcal{B}} (\ldots) \, \mathrm{d}V(\boldsymbol{x}) \,, \qquad \int_{\partial \mathcal{B}} (\ldots) = \int_{\partial \mathcal{B}} (\ldots) \, \mathrm{d}S(\boldsymbol{x}) \,.$$

- 2 Local differential formulation
 - Partial Differential Equation
 - Initial and boundary conditions
 - Initial-Boundary-Value Problem
- - Test functions
 - Weighted formulation and weak variational form
- - Approximation
 - Transient heat transfer (ordinary differential equations)
 - Stationary heat transfer (algebraic equations)

PDE for Heat Transfer Problem



Material data:

$$\begin{array}{l} \varrho = \varrho(\textbf{\textit{x}}) - \text{the density } \left[\frac{\text{kg}}{\text{m}^3}\right] \\ c = c(\textbf{\textit{x}}) - \text{the thermal capacity } \left[\frac{\text{J}}{\text{kg} \cdot \text{K}}\right] \\ k = k(\textbf{\textit{x}}) - \text{the thermal conductivity } \left[\frac{\text{W}}{\text{m} \cdot \text{K}}\right] \end{array}$$

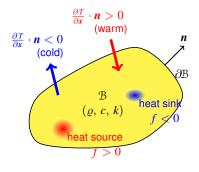
Known fields:

$$f = f(\mathbf{x}, t)$$
 – the heat production rate $\left[\frac{\mathrm{W}}{\mathrm{m}^3}\right]$ $u_i = u_i(\mathbf{x}, t)$ – the convective velocity $\left[\frac{\mathrm{W}}{\mathrm{s}}\right]$

The unknown field:

$$T = T(x, t) = ?$$
 – the temperature [K]

PDE for Heat Transfer Problem



Material data:

$$arrho = arrho(x)$$
 – the density $\left[rac{\mathrm{kg}}{\mathrm{m}^3}
ight]$ $c = c(x)$ – the thermal capacity $\left[rac{\mathrm{J}}{\mathrm{kg}\cdot\mathrm{K}}
ight]$ $k = k(x)$ – the thermal conductivity $\left[rac{\mathrm{W}}{\mathrm{m}\cdot\mathrm{K}}
ight]$

Known fields:

$$f = f(\mathbf{x}, t)$$
 – the heat production rate $\left[\frac{\mathrm{W}}{\mathrm{m}^3}\right]$ $u_i = u_i(\mathbf{x}, t)$ – the convective velocity $\left[\frac{\mathrm{W}}{\mathrm{s}}\right]$

The unknown field:

$$T = T(x, t) = ?$$
 – the temperature [K]

Heat transfer equation

$$\varrho\, c\, \overset{\bullet}{T} + q_{i|i} - f = 0 \quad \text{where the heat flux vector } \left[\frac{\mathtt{W}}{\mathtt{K}}\right] \colon$$

$$q_i = q_i(T) = \begin{cases} -k\, T_{|i} & -\text{ for conduction (only),} \\ -k\, T_{|i} + \varrho\, c\, u_i\, T & -\text{ for conduction and convection,} \end{cases}$$

and $\overset{\bullet}{T} = \frac{\partial T}{\partial t}$ is the time rate of change of temperature $\left[\frac{\mathbf{K}}{\mathbf{s}}\right]$.

Initial and boundary conditions

The initial condition (at $t = t_0$)

$$T(x,t_0) = T_0(x)$$
 in \mathcal{B}

Prescribed field:

$$T_0 = T_0(x)$$
 – the initial temperature [K]

Initial and boundary conditions

The initial condition (at $t = t_0$)

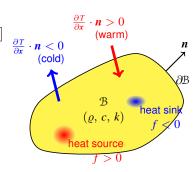
 $T(x,t_0) = T_0(x)$ in \mathcal{B}

Prescribed field:

$$T_0 = T_0(x)$$
 – the initial temperature [K]

The boundary conditions (on ∂B)

- the Dirichlet type: $T(\mathbf{x},t) = \hat{T}(\mathbf{x},t)$ on $\partial \mathbb{B}_T$
- the Neumann type: $-q_i(T(\mathbf{x},t)) n_i = \hat{q}(\mathbf{x},t)$ on $\partial \mathbb{B}_q$



Prescribed fields:

$$\hat{T} = \hat{T}(\mathbf{x},t)$$
 – the temperature $\left[\mathbf{K}\right]$ $\hat{q} = \hat{q}(\mathbf{x},t)$ – the inward heat flux $\left[\frac{\mathbf{W}}{\mathbf{m}^2}\right]$

Initial-Boundary-Value Problem

IBVP of the heat transfer

Find T = T(x, t) for $x \in \mathcal{B}$ and $t \in [t_0, t_1]$ satisfying the **equation of** heat transfer by conduction (a), or by conduction and convection (b):

$$\varrho\,c\,\mathring{T} + q_{i|i} - f = 0 \quad \text{where} \quad q_i = q_i(T) = \begin{cases} -k\,T_{|i} & \leftarrow \text{ (a)} \\ -k\,T_{|i} + \varrho\,c\,u_i\,T & \leftarrow \text{ (b)} \end{cases}$$

with the initial condition (at $t = t_0$):

$$T(\mathbf{x},t_0)=T_0(\mathbf{x})$$
 in \mathcal{B} ,

and subject to the boundary conditions:

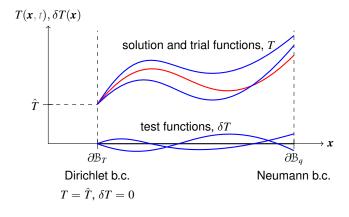
$$T(\mathbf{x},t) = \hat{T}(\mathbf{x},t)$$
 on $\partial \mathbb{B}_T$, $-q_i(T(\mathbf{x},t)) n_i = \hat{q}(\mathbf{x},t)$ on $\partial \mathbb{B}_q$,

where $\partial \mathbb{B}_T \cup \partial \mathbb{B}_q = \partial \mathbb{B}$ and $\partial \mathbb{B}_T \cap \partial \mathbb{B}_q = \emptyset$.

Notation remarks

- - Partial Differential Equation
 - Initial and boundary conditions
 - Initial-Boundary-Value Problem
- Global integral formulations
 - Test functions
 - Weighted formulation and weak variational form
- - Approximation
 - Transient heat transfer (ordinary differential equations)
 - Stationary heat transfer (algebraic equations)

Test functions



Test function $\delta T(x)$ is an arbitrary (but sufficiently regular) function defined in B, which meets the *admissibility condition*:

$$\delta T = 0$$
 on $\partial \mathbb{B}_T$.

Notice that **test functions** are always time-independent.

Weighted integral formulation

Notation remarks

$$\left(\int\limits_{\mathcal{B}} \Big(\varrho\, c\, \mathring{T} + q_{i|i} - f \Big) \delta T = 0 \quad \text{(for every } \delta T \text{)} \right)$$

Weighted integral formulation

Notation remarks

$$\left(\int\limits_{\mathbb{B}}\varrho\,c\,\mathring{T}\,\delta T+\int\limits_{\mathbb{B}}q_{i|i}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\quad \text{(for every δT)}\right)$$

The term $q_{i|i}$ introduces the second derivative of T: $q_{i|i} = -k T_{|ii} + \dots$ However, the heat PDE needs to be satisfied in the integral sense. Therefore, the requirements for T can be **weaken** as follows.

Weighted integral formulation

Notation remarks

$$\int\limits_{\mathcal{B}} \varrho \, c \, \dot{\tilde{T}} \, \delta T + \int\limits_{\mathcal{B}} q_{i|i} \, \delta T - \int\limits_{\mathcal{B}} f \, \delta T = 0 \quad \text{(for every } \delta T \text{)}$$

The term $q_{i|i}$ introduces the second derivative of T: $q_{i|i} = -k T_{|ii} + \dots$ However, the heat PDE needs to be satisfied in the integral sense. Therefore, the requirements for T can be **weaken** as follows.

Integrating by parts (using the divergence theorem)

$$\int\limits_{\mathcal{B}} q_{i|i} \, \delta T = \int\limits_{\mathcal{B}} (q_i \, \delta T)_{|i} - \int\limits_{\mathcal{B}} q_i \, \delta T_{|i} = \int\limits_{\partial \mathcal{B}} q_i \, \delta T \, n_i - \int\limits_{\mathcal{B}} q_i \, \delta T_{|i}$$

Weighted integral formulation

$$\left(\int\limits_{\mathbb{B}} \varrho \, c \, \mathring{T} \, \delta T + \int\limits_{\mathbb{B}} q_{i|i} \, \delta T - \int\limits_{\mathbb{B}} f \, \delta T = 0 \quad \text{(for every } \delta T) \right)$$

The term $q_{i|i}$ introduces the second derivative of T: $q_{i|i} = -k T_{|ii} + \dots$ However, the heat PDE needs to be satisfied in the integral sense. Therefore, the requirements for T can be **weaken** as follows.

Integrating by parts (using the divergence theorem)

$$\int_{\mathcal{B}} q_{i|i} \, \delta T = \int_{\mathcal{B}} (q_i \, \delta T)_{|i} - \int_{\mathcal{B}} q_i \, \delta T_{|i} = \int_{\partial \mathcal{B}} q_i \, \delta T \, n_i - \int_{\mathcal{B}} q_i \, \delta T_{|i}$$

Using the Neumann b.c and the property of test function

$$\int_{\partial \mathbb{B}} q_i \, n_i \, \delta T = \int_{\partial \mathbb{B}_q} \underbrace{q_i \, n_i}_{-\hat{q}} \, \delta T + \int_{\partial \mathbb{B}_T} q_i \, n_i \underbrace{\delta T}_{0} = - \int_{\partial \mathbb{B}_q} \hat{q} \, \delta T$$

Weighted integral formulation

$$\left(\int_{\mathbb{B}} \varrho \, c \, \mathring{T} \, \delta T + \int_{\mathbb{B}} q_{i|i} \, \delta T - \int_{\mathbb{B}} f \, \delta T = 0 \quad \text{(for every } \delta T\text{)}\right)$$

The term $q_{i|i}$ introduces the second derivative of T: $q_{i|i} = -k T_{|ii} + \dots$. However, the heat PDE needs to be satisfied in the integral sense. Therefore, the requirements for T can be **weaken** as follows.

After integrating by parts and using the Neumann boundary condition

$$\int_{\mathcal{B}} q_{i|i} \, \delta T = -\int_{\partial \mathbb{B}_q} \hat{q} \, \delta T - \int_{\mathcal{B}} q_i \, \delta T_{|i|}$$

Weak variational form

$$\left(\int\limits_{\mathbb{B}}\varrho\,c\,\mathring{T}\,\delta T-\int\limits_{\mathbb{B}}q_i\,\delta T_{|i}-\int\limits_{\partial\mathbb{B}_q}\hat{q}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\quad\text{(for every δT)}\right)$$

Matrix formulations

Weighted integral formulation

Notation remarks

$$\left(\int\limits_{\mathbb{B}}\varrho\,c\,\mathring{T}\,\delta T+\int\limits_{\mathbb{B}}q_{i|i}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\quad \text{(for every δT)}\right)$$

The term $q_{i|i}$ introduces the second derivative of T: $q_{i|i} = -k T_{|ii} + \dots$. However, the heat PDE needs to be satisfied in the integral sense. Therefore, the requirements for T can be **weaken** as follows.

Weak variational form

$$\left(\int\limits_{\mathbb{B}}\varrho\,c\,\overset{\bullet}{T}\,\delta T-\int\limits_{\mathbb{B}}q_i\,\delta T_{|i}-\int\limits_{\partial\mathbb{B}_q}\hat{q}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\quad\text{(for every δT)}\right)$$

Now, only the first order spatial-differentiability of T is required.

In this formulation the Neumann boundary condition is already met (it has been used in a *natural* way). Therefore, the only additional requirements are the Dirichlet boundary condition and the initial condition.

- - Partial Differential Equation
 - Initial and boundary conditions
 - Initial-Boundary-Value Problem
- - Test functions
 - Weighted formulation and weak variational form
- **Matrix formulations**
 - Approximation
 - Transient heat transfer (ordinary differential equations)
 - Stationary heat transfer (algebraic equations)

Approximation functions and space

The spatial approximation of solution in the domain \mathcal{B} is accomplished by a linear combination of (global) **shape functions**, $\phi_s = \phi_s(\mathbf{x})$,

$$T(\mathbf{x},t) = \theta_s(t) \, \phi_s(\mathbf{x})$$
 $(s = 1, ... N; \text{ summation over } s)$

where $\theta_s(t)$ [K] are (time-dependent) coefficients – the **degrees of freedom** (N is the total number of degrees of freedom). Consistent result is obtained now for the time rate of temperature

$$\dot{T}(x,t) = \dot{\theta}_s(t) \, \phi_s(x)$$
 where $\dot{\theta}_s(t) = \frac{\mathrm{d} \theta_s(t)}{\mathrm{d} t} \, \left[\frac{\mathrm{K}}{\mathrm{s}} \right]$.

Approximation functions and space

The spatial approximation of solution in the domain \mathcal{B} is accomplished by a linear combination of (global) **shape functions**, $\phi_s = \phi_s(\mathbf{x})$,

$$T(\mathbf{x},t) = \theta_s(t) \, \phi_s(\mathbf{x})$$
 $(s = 1, \dots N; \text{ summation over } s)$

where $\theta_s(t)$ [K] are (time-dependent) coefficients – the **degrees of freedom** (N is the total number of degrees of freedom). Consistent result is obtained now for the time rate of temperature

$$\dot{T}(\mathbf{x},t) = \dot{\theta}_s(t) \, \phi_s(\mathbf{x}) \quad \text{where} \quad \dot{\theta}_s(t) = \frac{\mathrm{d}\theta_s(t)}{\mathrm{d}t} \, \left[\frac{\mathrm{K}}{\mathrm{s}}\right].$$

Distinctive feature of the Galerkin method:

The same shape functions are used to approximate the solution as well as the test function, namely

$$\delta T(\mathbf{x}) = \delta \theta_r \, \phi_r(\mathbf{x})$$
 $(r = 1, \dots N; \text{ summation over } r)$.

Notation remarks

Transient heat transfer (system of ODEs)

To reduce the "regularity" requirements for solution the approximations

$$T = \theta_s \, \phi_s \quad \left(\dot{T} = \dot{\theta}_s \, \phi_s \right), \qquad \delta T = \delta \theta_r \, \phi_r$$

$$\int\limits_{\mathbb{B}}\varrho\,c\,\mathring{T}\,\delta T-\int\limits_{\mathbb{B}}q_{i}\,\delta T_{|i}-\int\limits_{\partial\mathbb{B}_{q}}\hat{q}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\,.$$

To reduce the "regularity" requirements for solution the approximations

$$T = heta_s \, \phi_s \quad \left(\mathbf{\mathring{T}} = \mathbf{\mathring{\theta}}_s \, \phi_s \right), \qquad \delta T = \delta heta_r \, \phi_r$$

$$\int\limits_{\mathbb{B}}\varrho\,c\,\mathring{T}\,\delta T-\int\limits_{\mathbb{B}}q_{i}\,\delta T_{|i}-\int\limits_{\partial\mathbb{B}_{q}}\hat{q}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\,.$$

$$1 \int_{\mathcal{B}} \varrho \, c \, \dot{T} \, \delta T = \dot{\theta}_s \, \delta \theta_r \int_{\mathcal{B}} \varrho \, c \, \phi_s \, \phi_r = \dot{\theta}_s \, \delta \theta_r \, M_{rs}$$

To reduce the "regularity" requirements for solution the approximations

$$T = \theta_s \, \phi_s \quad \left(\mathbf{\hat{T}} = \mathbf{\hat{\theta}}_s \, \phi_s \right), \qquad \delta T = \delta \theta_r \, \phi_r$$

$$\int\limits_{\mathbb{B}}\varrho\,c\,\mathring{T}\,\delta T-\int\limits_{\mathbb{B}}q_{i}\,\delta T_{|i}-\int\limits_{\partial\mathbb{B}_{q}}\hat{q}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\,.$$

$$\int_{\mathcal{B}} \varrho \, c \, \dot{T} \, \delta T = \dot{\theta}_s \, \delta \theta_r \int_{\mathcal{B}} \varrho \, c \, \phi_s \, \phi_r = \dot{\theta}_s \, \delta \theta_r \, M_{rs}$$

$$\int_{\mathcal{B}} q_i \, \delta T_{|i} = \int_{\mathcal{B}} \left(-k \, T_{|i} + \varrho \, c \, u_i \, T \right) \, \delta T_{|i} = \theta_s \, \delta \theta_r \int_{\mathcal{B}} \left(-k \, \phi_{s|i} + \varrho \, c \, u_i \, \phi_s \right) \, \phi_{r|i} \\
= \theta_s \, \delta \theta_r \, K_{rs}$$

To reduce the "regularity" requirements for solution the approximations

$$T = heta_s \, \phi_s \quad \left(\stackrel{ullet}{T} = \stackrel{ullet}{ heta_s} \, \phi_s
ight), \qquad \delta T = \delta heta_r \, \phi_r$$

$$\int\limits_{\mathbb{B}}\varrho\,c\,\mathring{T}\,\delta T-\int\limits_{\mathbb{B}}q_{i}\,\delta T_{|i}-\int\limits_{\partial\mathbb{B}_{q}}\hat{q}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\,.$$

$$\int_{\mathcal{B}} q_i \, \delta T_{|i} = \int_{\mathcal{B}} \left(-k \, T_{|i} + \varrho \, c \, u_i \, T \right) \, \delta T_{|i} = \theta_s \, \delta \theta_r \int_{\mathcal{B}} \left(-k \, \phi_{s|i} + \varrho \, c \, u_i \, \phi_s \right) \, \phi_{r|i} \\
= \theta_s \, \delta \theta_r \, K_{rs}$$

$$\int_{\partial \mathbb{B}_q} \hat{q} \, \delta T = \delta \theta_r \int_{\partial \mathbb{B}_q} \hat{q} \, \phi_r = \delta \theta_r \, Q_r$$

To reduce the "regularity" requirements for solution the approximations

$$T = heta_s \, \phi_s \quad \left(\stackrel{ullet}{T} = \stackrel{ullet}{ heta_s} \, \phi_s
ight), \qquad \delta T = \delta heta_r \, \phi_r$$

Global integral formulations

$$\int\limits_{\mathcal{B}}\varrho\,c\,\mathring{T}\,\delta T - \int\limits_{\mathcal{B}}q_i\,\delta T_{|i} - \int\limits_{\partial\mathcal{B}_q}\hat{q}\,\delta T - \int\limits_{\mathcal{B}}f\,\delta T = 0\,.$$

$$\int_{\mathcal{B}} \varrho \, c \, \dot{T} \, \delta T = \dot{\theta}_s \, \delta \theta_r \int_{\mathcal{B}} \varrho \, c \, \phi_s \, \phi_r = \dot{\theta}_s \, \delta \theta_r \, M_{rs}$$

$$\int_{\mathcal{B}} q_i \, \delta T_{|i} = \int_{\mathcal{B}} \left(-k \, T_{|i} + \varrho \, c \, u_i \, T \right) \, \delta T_{|i} = \theta_s \, \delta \theta_r \int_{\mathcal{B}} \left(-k \, \phi_{s|i} + \varrho \, c \, u_i \, \phi_s \right) \, \phi_{r|i} \\
= \theta_s \, \delta \theta_r \, K_{rs}$$

$$\int\limits_{\partial \mathbb{B}_q} \hat{q} \, \delta T = \delta \theta_r \int\limits_{\partial \mathbb{B}_q} \hat{q} \, \phi_r = \delta \theta_r \, Q_r$$

$$\int_{\mathbb{R}} f \, \delta T = \delta \theta_r \int_{\mathbb{R}} f \, \phi_r = \delta \theta_r F_r$$

Matrix formulation of the heat transfer problem

$$\left[M_{rs}\stackrel{\bullet}{ heta}_s-K_{rs}\, heta_s-(Q_r+F_r)
ight]\delta heta_r=0 \quad ext{for every }\delta heta_r.$$

This produces the following system of first-order **ordinary differential equations** (for $\theta_s = \theta_s(t) = ?$):

$$\left[M_{rs}\,\dot{ heta}_s-K_{rs}\, heta_s=(Q_r+F_r)
ight] \qquad (r,s=1,\ldots N).$$

Matrix formulation of the heat transfer problem

$$\big[M_{rs}\overset{\bullet}{\theta}_s-K_{rs}\,\theta_s-(Q_r+F_r)\big]\delta\theta_r=0\quad\text{for every }\delta\theta_r.$$

This produces the following system of first-order **ordinary differential equations** (for $\theta_s = \theta_s(t) = ?$):

$$M_{rs} \dot{\theta}_s - K_{rs} \theta_s = (Q_r + F_r)$$
 $(r, s = 1, \dots N).$

- $lackbox{\blacksquare} M_{rs} = \int\limits_{\mathcal{B}} \varrho\, c\, \phi_s\, \phi_r \,\,$ the thermal capacity matrix $\left[rac{1}{\mathrm{K}}
 ight],$
- $lacklossim Q_r = \int\limits_{\partial B_r} \hat{q} \, \phi_r \, ext{the inward heat flow vector } [w],$
- $lackbox{\blacksquare} F_r = \int \! f \, \phi_r \, \, \, \, {
 m the \ heat \ production \ vector \ [W]} \, .$

$$T = T(\mathbf{x}), \qquad f = f(\mathbf{x}), \qquad u_i = u_i(\mathbf{x}) \qquad (\text{for } \mathbf{x} \in \mathcal{B}).$$

BVP of stationary heat flow: Find T = T(x) satisfying (in \mathcal{B})

$$q_{i|i} - f = 0$$
 where:

$$q_i = q_i(T) = egin{cases} -k\,T_{|i} & ext{(no convection),} \ -k\,T_{|i} + arrho\,c\,u_i\,T & ext{(with convection),} \end{cases}$$

with boundary conditions:

$$T = \hat{T}$$
 on $\partial \mathbb{B}_T$ (Dirichlet), $-q_i(T) n_i = \hat{q}$ on $\partial \mathbb{B}_q$ (Neumann).

The weak variational form lacks the rate integrand

$$-\int\limits_{\mathbb{B}}q_{i}\,\delta T_{|i}-\int\limits_{\partial\mathbb{B}_{a}}\hat{q}\,\delta T-\int\limits_{\mathbb{B}}f\,\delta T=0\,.$$

■ The approximations $T(x) = \theta_s \phi_s(x)$, $\delta T(x) = \delta \theta_r \phi_r(x)$ lead to the following system of linear algebraic equations (for $\theta_s = ?$):

$$\left(-K_{rs}\,\theta_s=(Q_r+F_r)\right) \qquad (r,s=1,\ldots N).$$