

Exercise 4.1

Displacement formulation of linear elastodynamics: strong and weak forms, Galerkin FE model

General IBVP of linear elastodynamics

Find $u_i = u_i(\mathbf{x}, t) = ?$, $\varepsilon_{ij} = \varepsilon_{ij}(\mathbf{x}, t) = ?$, $\sigma_{ij} = \sigma_{ij}(\mathbf{x}, t) = ?$ satisfying in Ω :

$$\sigma_{ij|j} + f_i = \rho \ddot{u}_i, \quad \varepsilon_{ij} = \frac{1}{2}(u_{i|j} + u_{j|i}), \quad \sigma_{ij} = \begin{cases} C_{ijkl} \varepsilon_{kl} & (\text{anisotropy}), \\ 2\mu \varepsilon_{ij} + \lambda \varepsilon_{kk} \delta_{ij} & (\text{isotropy}), \end{cases}$$

with the initial conditions (at $t = t_0$):

$$u_i(\mathbf{x}, t_0) = u_i^0(\mathbf{x}) \quad \text{and} \quad \dot{u}_i(\mathbf{x}, t_0) = v_i^0(\mathbf{x}) \quad \text{in } \Omega,$$

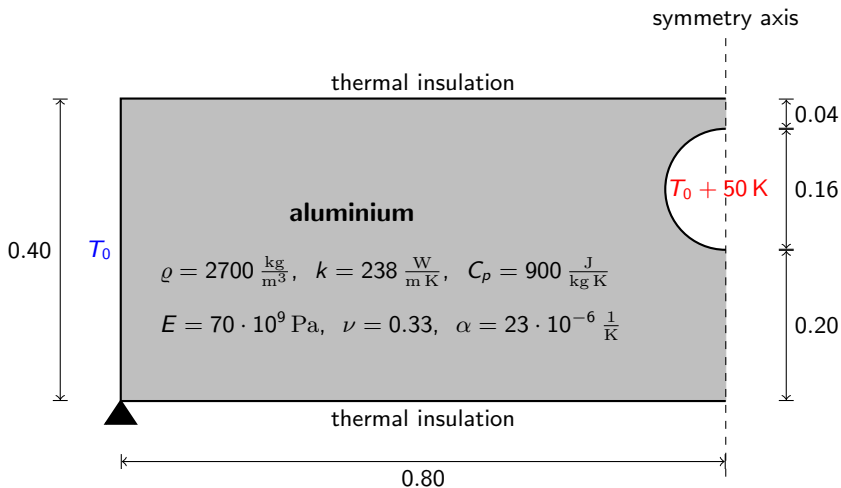
and subject to the boundary conditions on $\Gamma = \Gamma_u \cup \Gamma_t$ ($\Gamma_u \cap \Gamma_t = \emptyset$):

$$u_i(\mathbf{x}, t) = \hat{u}_i(\mathbf{x}, t) \quad \text{on } \Gamma_u, \quad \sigma_{ij}(\mathbf{x}, t) n_j = \hat{t}_i(\mathbf{x}, t) \quad \text{on } \Gamma_t.$$

- 1 Derive the displacement formulation of elasticity (Navier's equations)
- 2 Derive the weak variational form of the displacement formulation
- 3 Derive the Galerkin FE model (i.e., $\mathbf{M} \ddot{\mathbf{q}}(t) + \mathbf{K} \mathbf{q}(t) = \mathbf{Q}(t)$)

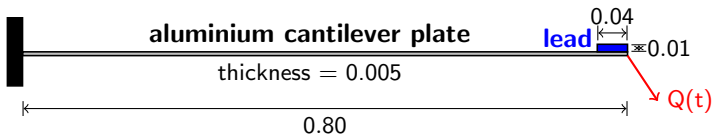
Exercise 4.2

A simple thermo-elastic problem



Exercise 4.3

Using the Weak Form PDE Interface in COMSOL Multiphysics



$$\rho_{Al} = 2700 \frac{\text{kg}}{\text{m}^3},$$

$$E_{Al} = 70 \cdot 10^9 \text{ Pa},$$

$$\nu_{Al} = 0.33,$$

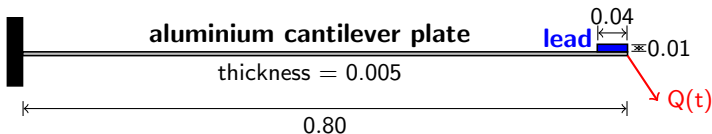
$$\rho_{Pb} = 11340 \frac{\text{kg}}{\text{m}^3},$$

$$E_{Pb} = 16 \cdot 10^9 \text{ Pa},$$

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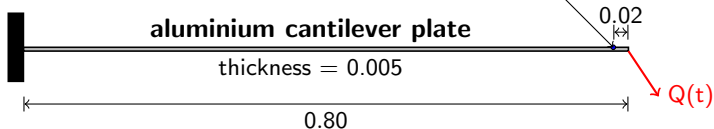
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concentrated mass weak term

$$m_{Pb} = \rho_{Pb} \cdot 0.04 \text{ [m]} \cdot 0.01 \text{ [m]}$$



Exercise 4.3

Using the Weak Form PDE Interface in COMSOL Multiphysics

Weak form for harmonic linear elasticity

$$\omega^2 \int_{\Omega} \rho \mathbf{u}_i \delta \mathbf{u}_i - \int_{\Omega} \sigma_{ij} \delta \mathbf{u}_{i|j} + \int_{\Omega} \mathbf{f}_i \delta \mathbf{u}_i + \int_{\Gamma_t} \hat{\mathbf{t}}_i \delta \mathbf{u}_i = 0$$

Here: $\sigma_{ij} = \sigma_{ij}(\mathbf{u}) = \begin{cases} C_{ijkl} u_{k|l} & \text{– for anisotropic material} \\ \mu (u_{i|j} + u_{j|i}) + \lambda u_{k|k} \delta_{ij} & \text{– for isotropic material} \end{cases}$

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Weak form for harmonic linear elasticity

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■ Constants:

$$\omega = 2\pi f$$

$$\mu = E/2/(1+\nu) \quad \lambda = \nu E/(1+\nu)/(1-2\nu)$$

■ Domain expressions (for an isotropic material):

$$s_{11} = 2\mu u_{1x} + \lambda (u_{1x} + u_{2y})$$

$$s_{22} = 2\mu u_{2y} + \lambda (u_{1x} + u_{2y})$$

$$s_{12} = \mu (u_{1y} + u_{2x})$$

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- Domain integrand (in Ω):

$$\begin{aligned} & \omega^2 \rho * (u1 * test(u1) + u2 * test(u2)) \\ & - s11 * test(u1x) - s12 * test(u1y + u2x) - s22 * test(u2y) \\ & f1 * test(u1) + f2 * test(u2) \end{aligned}$$

- Neumann boundary integrand (on Γ_t):

$$t1 * test(u1) + t2 * test(u2)$$

- Concentrated mass weak term:

$$\omega^2 \text{mass} * (u1 * test(u1) + u2 * test(u2))$$