

LONG WAVE GENERATION ABOVE A CYLINDRICAL SILL

Themistoklis S. Stefanakis^{1,2 †} & Frédéric Dias^{1,2}

¹*School of Mathematical Sciences, University College of Dublin, Ireland*

²*CMLA, ENS Cachan, 61 avenue du Président Wilson, 94235 Cachan cedex, France*

Summary Waves generated in a two-horizontal-dimension fluid domain of uniform depth by a deformation of the bottom boundary was elegantly studied by Hammack [3]. In the current paper we investigate the effect of bathymetry by analytically solving the forced Linear Shallow Water Equations (LSWE) when the bathymetry consists of a cylindrical sill sitting on a flat bottom. We use Hammack's seafloor deformation and we follow a similar approach as Renzi & Sammarco [4].

WAVE DESCRIPTION

The bathymetry consists of a cylinder of radius r_c^* and height h_c^* (starred quantities are dimensional), sitting on an indefinite horizontal surface. The depth when $r^* < r_c^*$ is h_1^* while otherwise it is h_2^* . The seafloor is vertically uniformly displaced at the circular area defined by $r_0^* > r_c^*$. We use the following non-dimensionalization:

$$r = r^*/r_c^*, \quad t = \sqrt{\frac{g}{r_c^*}} t^*, \quad \zeta = \zeta^*/f_0^*, \quad f = f^*/f_0^*, \quad h = h^*/h_c^* \quad (1)$$

where f_0^* is the maximum vertical displacement of the seafloor. The forcing term is $f(r, t) = (1 - e^{-\gamma t})\mathcal{H}(r_0 - r)$, $t > 0$ with $r_0 > 1$, $\mathcal{H}$ the Heaviside function and γ a coefficient that defines the speed of the displacement. The forced LSWE in polar coordinates (r, θ) is

$$\zeta_{tt} - h \left(\frac{1}{r} \zeta_r + \zeta_{rr} + \frac{1}{r^2} \zeta_{\theta\theta} \right) - h_r \zeta_r = f_{tt} \quad (2)$$

where $\zeta(r, \theta, t)$ is the free-surface elevation, t is the time and $h(r)$ is the bottom depth with respect to the undisturbed free-surface $z = 0$. We employ the Laplace transform with complex ω being the non-dimensional transform parameter. The transformed Eqn. (2) yields

$$r^2 \hat{\zeta}_{rr} + r \left(1 + r \frac{h_r}{h} \right) \hat{\zeta}_r - \frac{\omega^2 r^2}{h} \hat{\zeta} + \hat{\zeta}_{\theta\theta} = -\frac{r^2}{h} \hat{f}_{tt}, \quad \hat{f}_{tt} = \int_0^\infty f_{tt}(r, \theta, t) e^{-\omega t} dt \quad (3)$$

The near field ($r^* < r_c^*$; $r < 1$) in the transformed space

Since in the near field $h = h_1^*/h_c^* \doteq c_d$ and everything is axisymmetric, Eqn. (3) becomes

$$r^2 \hat{\zeta}_{rr} + r \hat{\zeta}_r - \frac{\omega^2 r^2}{c_d} \hat{\zeta} = -\frac{r^2}{c_d} \hat{f}_{tt} \quad (4)$$

If we take the homogeneous form of Eqn. (4) (by setting zero the right hand side) it is straightforward to see that the above equation becomes a standard modified Bessel equation of zero-th order, whose solutions are the two modified Bessel functions I_0 and K_0 . The general solution of the homogeneous equation has a branch-cut on the negative real axis of the complex plane ω introduced by K_0 . Boundedness of the free-surface elevation at $x = 0$ requires the solution to depend only on I_0 . In order to find the solution of the inhomogeneous equation (4) we employ the method of variation of parameters. Hence the solution of the forced ordinary differential equation (4) is

$$\hat{\zeta}(r; \omega) = \alpha_1 I_0 \left(\frac{\omega r}{\sqrt{c_d}} \right) - P(r; \omega) \quad (5)$$

$$\text{where } P(r; \omega) = \int_0^r \frac{\hat{f}_{tt}(\rho; \omega)}{c_d W_1(\rho; \omega)} \left[I_0 \left(\frac{\omega \rho}{\sqrt{c_d}} \right) K_0 \left(\frac{\omega r}{\sqrt{c_d}} \right) - I_0 \left(\frac{\omega r}{\sqrt{c_d}} \right) K_0 \left(\frac{\omega \rho}{\sqrt{c_d}} \right) \right] d\rho \quad (6)$$

is the particular solution and $W_1(\rho; \omega) = \sqrt{c_d}/\omega \rho$ is the Wronskian [1] of the two homogeneous solutions.

The far field ($r^* > r_c^*$; $r > 1$) in the transformed space

In the far field $h = h_2^*/h_c^* = 1 + c_d \doteq k_d$. By performing the same kind of analysis as for the near field, one can show that

$$\hat{\zeta}(r; \omega) = \beta_2 K_0 \left(\frac{\omega r}{\sqrt{k_d}} \right) - \Pi(r; \omega) \quad (7)$$

[†]Corresponding author. E-mail: themistoklisstef@yahoo.co.uk.

$$\text{where } \Pi(r; \omega) = \int_1^r \frac{\hat{f}_{tt}(\rho; \omega)}{k_d W_2(\rho; \omega)} \left[I_0 \left(\frac{\omega \rho}{\sqrt{k_d}} \right) K_0 \left(\frac{\omega r}{\sqrt{k_d}} \right) - I_0 \left(\frac{\omega r}{\sqrt{k_d}} \right) K_0 \left(\frac{\omega \rho}{\sqrt{k_d}} \right) \right] d\rho \quad (8)$$

is the particular solution and $W_2(\rho; \omega) = \sqrt{k_d}/\omega\rho$ is the Wronskian [1].

Matching at $r = 1$

By matching the free-surface elevation and the radial fluxes at $r = 1$ we obtain the expressions for α_1 and β_2 :

$$\begin{aligned} \alpha_1(\omega) &= \frac{\hat{f}_{tt}}{\sqrt{c_d}} \left[\frac{1}{\sqrt{c_d}} \frac{W \left(K_0 \left(\frac{\omega}{\sqrt{c_d}} \right), K_0 \left(\frac{\omega}{\sqrt{k_d}} \right) \right)}{W \left(I_0 \left(\frac{\omega}{\sqrt{c_d}} \right), K_0 \left(\frac{\omega}{\sqrt{k_d}} \right) \right)} I_1 \left(\frac{\omega}{\sqrt{c_d}} \right) - \frac{1}{\omega} + \frac{1}{\sqrt{c_d}} K_1 \left(\frac{\omega}{\sqrt{c_d}} \right) \right] \\ \beta_2(\omega) &= \frac{1}{\omega \sqrt{c_d}} \frac{\hat{f}_{tt} I_1 \left(\frac{\omega}{\sqrt{c_d}} \right)}{W \left(K_0 \left(\frac{\omega}{\sqrt{k_d}} \right), I_0 \left(\frac{\omega}{\sqrt{c_d}} \right) \right)} \end{aligned} \quad (9)$$

where W denotes the Wronskian. By employing the inverse Laplace transform we obtain the free-surface elevation in the physical space.

The near field ($r < 1$) in physical space

$$\begin{aligned} \zeta(r; t) &= \frac{1}{2\pi} \int_0^\infty \left\{ \frac{1}{i c_d \gamma - i \omega} \frac{\gamma^2}{\omega} \frac{W \left(\frac{i\pi}{2} H_0 \left(\frac{\omega}{\sqrt{c_d}} \right), \frac{i\pi}{2} H_0 \left(\frac{\omega}{\sqrt{k_d}} \right) \right)}{W \left(J_0 \left(\frac{\omega}{\sqrt{c_d}} \right), \frac{i\pi}{2} H_0 \left(\frac{\omega}{\sqrt{k_d}} \right) \right)} J_1 \left(\frac{\omega}{\sqrt{c_d}} \right) \right. \\ &\quad \left. + \frac{\gamma^2}{\gamma - i \omega} \frac{1}{i \omega \sqrt{c_d}} \left(1 - \frac{i \omega \pi}{2 \sqrt{c_d}} H_1 \left(\frac{\omega}{\sqrt{c_d}} \right) \right) \right\} J_0 \left(\frac{\omega r}{\sqrt{c_d}} \right) e^{-i \omega t} d\omega + c.c. \\ &\quad - \frac{1}{4} \int_0^r \int_0^\infty \frac{\gamma^2}{\gamma - i \omega} \frac{\omega \rho}{(c_d)^{3/2}} \left[J_0 \left(\frac{\omega \rho}{\sqrt{c_d}} \right) H_0 \left(\frac{\omega r}{\sqrt{c_d}} \right) - J_0 \left(\frac{\omega r}{\sqrt{c_d}} \right) H_0 \left(\frac{\omega \rho}{\sqrt{c_d}} \right) \right] e^{-i \omega t} d\omega d\rho - c.c. \end{aligned} \quad (10)$$

Where J_n is the Bessel function of first kind and order n , while H_n is the Hankel function of first kind and order n . C.c denotes the complex conjugate of the integral over ω .

The far field ($r > 1$) in physical space

$$\begin{aligned} \zeta(r; t) &= -\frac{1}{4} \int_0^\infty \frac{\gamma^2}{\gamma - i \omega} \frac{1}{i \omega \sqrt{c_d}} \frac{J_1 \left(\frac{\omega}{\sqrt{c_d}} \right) H_0 \left(\frac{\omega r}{\sqrt{c_d}} \right)}{W \left(\frac{i\pi}{2} H_0 \left(\frac{\omega}{\sqrt{k_d}} \right), J_0 \left(\frac{\omega}{\sqrt{c_d}} \right) \right)} e^{-i \omega t} d\omega - c.c. \\ &\quad - \frac{1}{4} \int_1^r \int_0^\infty \frac{\omega \rho}{(k_d)^{3/2}} \frac{\gamma^2}{\gamma - i \omega} \mathcal{H}(r_0 - r) \left[J_0 \left(\frac{\omega \rho}{\sqrt{k_d}} \right) H_0 \left(\frac{\omega r}{\sqrt{k_d}} \right) - J_0 \left(\frac{\omega r}{\sqrt{k_d}} \right) H_0 \left(\frac{\omega \rho}{\sqrt{k_d}} \right) \right] e^{-i \omega t} d\omega d\rho - c.c. \end{aligned} \quad (11)$$

DISCUSSION

The evolution of the free-surface elevation is analytically derived in terms of Bessel and Hankel functions. It is clear that a significant parameter is c_d which depends on the height of the sill and we are currently exploring its importance. The analytical solution will be compared to the solution derived by Hammack [3], when the seafloor is flat as well as to the numerical results of a nonlinear shallow water equations solver [2].

References

- [1] Abramowitz M. and Stegun I. A.: Handbook of Mathematical Functions. Dover, 1965.
- [2] Dutykh D., Poncet R. and Dias F.: The VOLNA Code for the Numerical Modeling of Tsunami Waves: Generation, Propagation and Inundation. *Eur. J. Mech. B/Fluid* **30**: 598–615.
- [3] Hammack J.: A Note on Tsunamis: Their Generation and Propagation in an Ocean of Uniform Depth. *J. Fluid Mech* **60**: 769–799, 1973.
- [4] Renzi E. and Sammarco P.: Landslide Tsunamis Propagating Around a Conical Island. *J. Fluid Mech* **650**: 251–285, 2010.